

Course Unit Descriptor

Study Programme: Biomedical engineering			
Course Unit Title: Basics of medical robotics			
Course Unit Code: BM116A			
Name of Lecturer(s): Nikolić Milutin			
Type and Level of Studies: Bachelor			
Course Status (compulsory/elective): elective			
Semester (winter/ summer): winter			
Language of instruction: english			
Mode of course unit delivery (face-to-face/distance learning): face-to-face			
Number of ECTS Allocated: 4			
Prerequisites: none			
Course Aims: The outcome of this course is to students understanding of robots working principles in biomedicine, as well as teach students to apply acquired knowledge in design of new robots.			
Learning Outcomes: - Understanding of working principles of various medical robots, - appropriate use of various medical robots, -ability to design simpler medical robots.			
Syllabus. History and application overview, Basic concepts and definitions of kinematic chain structure which are basis for more complex structures, kinematics of robots (direct and inverse problems), dynamics of robots, robot control, Specificities of medical robots, robots in surgery, prothetics, orthosis, Robots as assistive technology, robots for disabled, handicapped and old people. Robotic pets. Special robotic devices			
Required Reading:			
Weekly Contact Hours: 2	Lectures: 2	Practical work: 0	
Teaching Methods: Lectures. practicing, consultations			
Knowledge Assessment (maximum of 100 points):			
Pre-exam obligations	points	Final exam	points
Attendance			
Computer exercises			
Tests (4x)			

